



CAMBRIDGE ASSESSMENT

STEP Solutions 2010

Mathematics
STEP 9465/9470/9475

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Section A: Pure Mathematics

1. The first two parts are obtained by separating off the final term of the summation and expanding the brackets respectively giving $C = \frac{1}{n+1}(nA + x_{n+1})$, and

$$B = \frac{1}{n} \sum_{k=1}^n x_k^2 - A^2$$

(the latter given in the question) .

By comparison with the expression for B ,

$$D = \frac{1}{n+1} \sum_{k=1}^{n+1} x_k^2 - C^2$$

which by substituting for

$$\frac{1}{n} \sum_{k=1}^n x_k^2$$

from the expression for B gives

$$D = \frac{1}{n+1} [n(B + A^2) + x_{n+1}^2] - C^2$$

Substituting for C from the initial result, the required expression can be obtained which can most neatly be written

$$D = \frac{n}{(n+1)^2} [(n+1)B + (A - x_{n+1})^2]$$

Thus $(n+1)D = nB + \frac{n}{n+1}(A - x_{n+1})^2$ yielding the first inequality.

Also, $D - B = \frac{n}{(n+1)^2}(A - x_{n+1})^2 - \frac{1}{n+1}B$ and this quadratic expression is only negative if and only if $(A - x_{n+1})^2 < \frac{n+1}{n}B$.

Rearranging the inequality to make x_{n+1} the subject yields the required result.

2. The expression of $\cosh a$ in exponentials enables the integral to be written as

$$\int_0^1 \frac{1}{x^2 + x(e^a + e^{-a}) + 1} dx$$

which can in turn can be expressed as

$$\int_0^1 \frac{1}{(x + e^a)(x + e^{-a})} dx$$

and so employing partial fractions this is

$$\frac{1}{(e^a - e^{-a})} \left[\ln \left(\frac{x + e^{-a}}{x + e^a} \right) \right]_0^1$$

The evaluation of this with simplification of logarithms yields

$$\frac{1}{2 \sinh a} \left(\ln \left(e^a \frac{1 + e^a}{1 + e^{-a}} \right) \right)$$

giving the required result.

In part (ii), the same technique can be employed for both integrals giving, in the first case

$$\begin{aligned} & \int_1^{\infty} \frac{1}{(x + e^a)(x - e^{-a})} dx \\ &= \frac{1}{(e^a + e^{-a})} \left[\ln \left(\frac{x - e^{-a}}{x + e^a} \right) \right]_1^{\infty} \\ &= \frac{1}{2 \cosh a} \left(a + \ln \left(\coth \frac{a}{2} \right) \right) \end{aligned}$$

and in the second

$$\begin{aligned} & \int_0^{\infty} \frac{1}{(x^2 + e^a)(x^2 + e^{-a})} dx \\ &= \frac{1}{(e^a - e^{-a})} \left[\frac{1}{e^{-\frac{a}{2}}} \tan^{-1} \left(\frac{x}{e^{-\frac{a}{2}}} \right) - \frac{1}{e^{\frac{a}{2}}} \tan^{-1} \left(\frac{x}{e^{\frac{a}{2}}} \right) \right]_0^{\infty} \\ &= \frac{1}{2 \sinh a} \left(\frac{\pi}{2} 2 \sinh \frac{a}{2} \right) \end{aligned}$$

or alternatively

$$\frac{\pi}{4 \cosh \frac{a}{2}}$$

3. The two primitive 4th roots of unity are $\pm i$ so $C_4(x) = (x - i)(x + i) = x^2 + 1$

$$C_1(x) = x - 1, \quad x^2 - 1 = (x - 1)(x + 1) \quad \text{so } C_2(x) = x + 1,$$

$$x^3 - 1 = (x - 1)(x^2 + x + 1) \quad \text{so } C_3(x) = x^2 + x + 1$$

$$x^5 - 1 = (x - 1)(x^4 + x^3 + x^2 + x + 1) \quad \text{so } C_5(x) = x^4 + x^3 + x^2 + x + 1$$

$$x^6 - 1 = (x^3 - 1)(x^3 + 1) = (x^3 - 1)(x + 1)(x^2 - x + 1) \quad \text{so } C_6(x) = x^2 - x + 1$$

In part (ii), $C_n(x) = 0 \Rightarrow x^4 = -1 \Rightarrow x^8 = 1$ so n is a multiple of 8, and as there are 4 primitive 8th roots of unity, n must be 8.

$$x^p = 1 \Rightarrow x^p - 1 = 0 \Rightarrow (x - 1)(x^{p-1} + x^{p-2} + x^{p-3} + \dots + 1)$$

1 is the only non-primitive root as no power of any other root less than the p^{th} equals unity,

because p is prime, so $C_p(x) = x^{p-1} + x^{p-2} + x^{p-3} + \dots + 1$

No root of $C_n(x) = 0$ is a root of $C_t(x) = 0$ for any $t \neq n$. (For if $t < n$, by the definition of $C_n(x)$, there is no integer t such that $a^t = 1$ when $a^n = 1$. Similarly, if $t > n$.)

Thus if $C_q(x) \equiv C_r(x)C_s(x)$, and if $C_q(x) = 0$, then $C_r(x) = 0$ or $C_s(x) = 0$, so

$q = r$ or $q = s$.

If $q = r$, then $C_q(x) \equiv C_r(x)$, and so $C_s(x) \equiv 1$ which is not possible for positive s , and likewise in the alternative case.

4. (i) As α satisfies both equations, $\alpha^2 + a\alpha + b = 0$ and $\alpha^2 + c\alpha + d = 0$, so subtracting these the desired result is simply found.

If $(b-d)^2 - a(b-d)(a-c) + b(a-c)^2 = 0$, then we may divide by $(a-c)^2$, and find that $-\frac{(b-d)}{(a-c)}$ satisfies $x^2 + ax + b = 0$. But also,

$\left(\frac{(b-d)}{(a-c)}\right)^2 + c\left(-\frac{(b-d)}{(a-c)}\right) + d = \left(\frac{(b-d)}{(a-c)}\right)^2 + a\left(-\frac{(b-d)}{(a-c)}\right) + b + (c-a)\left(-\frac{(b-d)}{(a-c)}\right) + (d-b)$ and so $-\frac{(b-d)}{(a-c)}$ satisfies $x^2 + cx + d = 0$.

On the other hand if there is a common root, then it is found at the start of the question and as it satisfies $\alpha^2 + a\alpha + b = 0$, the required result is found.

If $(b-d)^2 - a(b-d)(a-c) + b(a-c)^2 = 0$ and $a = c$, then $b = d$ and so the two equations are one and trivially have a common root. Alternatively, if there is a common root and $a = c$, then the initial subtraction yields $b = d$, and so the result is trivially true.

(ii) If $(b-r)^2 - a(b-r)(a+b-q) + b(a+b-q)^2 = 0$, then $x^2 + ax + b = 0$ and $x^2 + (q-b)x + r = 0$ have a common root from (i), and so then do $x^2 + ax + b = 0$ and $x(x^2 + ax + b) + x^2 + (q-b)x + r = 0$ which is the required result.

On the other hand, if the two equations have a common root α , then $\alpha^2 + a\alpha + b = 0$ and $\alpha^3 + (a+1)\alpha^2 + q\alpha + r = 0$, and thus so does

$\alpha^3 + (a+1)\alpha^2 + q\alpha + r - \alpha(\alpha^2 + a\alpha + b) = 0$ which is a quadratic equation and we can use the result from (i) again.

Using $\alpha = \frac{5}{2}$, $q = \frac{5}{2}$, $r = \frac{1}{2}$, in the given condition, we obtain a cubic equation in b ,

$b^3 - \frac{3}{2}b^2 + \frac{1}{4}b + \frac{1}{4} = 0$, which has a solution $b = 1$, meaning the other two can be simply obtained as $b = \frac{1 \pm \sqrt{5}}{4}$.

5. The line CP can be shown to have equation $(1-n)y = x - an$ and so R is $\left(0, \frac{an}{n-1}\right)$

So, similarly, S must be $\left(\frac{am}{m-1}, 0\right)$.

Thus RS has equation $n(m-1)x + m(n-1)y = amn$ and PQ has equation $mx + ny = amn$. As the coordinates of T satisfy both equations, they satisfy their difference which is

$(mn - n - m)(x + y) = 0$. As RS and PQ intersect, $\frac{n}{m} \neq \frac{m(n-1)}{n(m-1)}$ which yields

$(m-n)(mn - m - n) \neq 0$ and hence $(mn - m - n) \neq 0$ implying that T's coordinates satisfy $x + y = 0$ giving the desired result. (Alternatively, $mn - m - n = 0 \Leftrightarrow n = \frac{m}{m-1} < 0$, which is a contradiction.)

The construction can be achieved more than one way, but one is to label the given square ABCD anti-clockwise, choose points on AB and AD different distances from A, label them P and Q, construct CP and CQ, and find their intersections with AD and AB, R and S, respectively, and find the intersection of PQ and RS, label it T, then TA is perpendicular to AC. Rotating the labelling through a right angle and repeating three more times achieves the desired square.

6. P_1 is $(\cos \varphi, \sin \varphi, 0)$, P_2 is $(\cos \varphi \cos \lambda, \sin \varphi \cos \lambda, \sin \lambda)$, Q_1 is $(-\sin \varphi, \cos \varphi, 0)$, Q_2 is $(-\sin \varphi, \cos \varphi, 0)$, R_1 is $(0,0,1)$ and R_2 is $(-\cos \varphi \sin \lambda, -\sin \varphi \sin \lambda, \cos \lambda)$.

The scalar product $OP_2 \cdot OP_0$ gives the quoted result immediately. The direction of the axis can

be found from the vector product $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} \cos \varphi \cos \lambda \\ \sin \varphi \cos \lambda \\ \sin \lambda \end{pmatrix}$ giving the direction of the axis as

$$\begin{pmatrix} 0 \\ -\sin \lambda \\ \sin \varphi \cos \lambda \end{pmatrix}.$$

7. The initial result can be obtained by differentiating y directly twice obtaining

$$\frac{dy}{dx} = -\sin(m \sin^{-1} x) \frac{m}{\sqrt{1-x^2}}$$

$$\frac{d^2y}{dx^2} = -\cos(m \sin^{-1} x) \frac{m^2}{1-x^2} - \sin(m \sin^{-1} x) \frac{mx}{(1-x^2)^{\frac{3}{2}}}$$
 and substituting into the LHS.

(Slightly more elegant is to rearrange as $\cos^{-1} y = m \sin^{-1} x$, differentiate and then square to

obtain $(1-x^2) \left(\frac{dy}{dx}\right)^2 = m^2(1-y^2)$ and then differentiate a second time.)

The two similar results are $(1-x^2) \frac{d^3y}{dx^3} - 3x \frac{d^2y}{dx^2} + (m^2-1) \frac{dy}{dx} = 0$ and

$$(1-x^2) \frac{d^4y}{dx^4} - 5x \frac{d^3y}{dx^3} + (m^2-4) \frac{d^2y}{dx^2} = 0,$$
 which lead to the conjecture

$$(1-x^2) \frac{d^{n+2}y}{dx^{n+2}} - (2n+1)x \frac{d^{n+1}y}{dx^{n+1}} + (m^2-n^2) \frac{d^ny}{dx^n} = 0$$
 which is proved simply by induction.

Using $= 0$, we find that $y = 1$, $\frac{dy}{dx} = 0$, $\frac{d^2y}{dx^2} = -m^2$, $\frac{d^3y}{dx^3} = 0$, $\frac{d^4y}{dx^4} = m^2(m^2-4)$

and so the Maclaurin series commences $y = 1 - \frac{m^2}{2!}x^2 + \frac{m^2(m^2-2^2)}{4!}x^4 + \dots$

Now replacing x by $\sin \theta$,

$$\cos m\theta = 1 - \frac{m^2}{2!}x^2 + \frac{m^2(m^2-2^2)}{4!}x^4 + \dots = 1 - \frac{m^2}{2!}\sin^2 \theta + \frac{m^2(m^2-2^2)}{4!}\sin^4 \theta + \dots$$

All the odd differentials are zero, and the even ones are $(-1)^{k+1}m^2(m^2-2^2) \dots (m^2-(2k)^2)$, so if m is even all the terms are zero from a certain point (when $m = 2k$) and thus the series terminates and is a polynomial in $\sin \theta$, of degree m .

8. Substituting for $P(x)$, the desired integral is seen to be the reverse of the quotient rule, i.e.

$$\frac{R(x)}{Q(x)} (+k)$$

To choose a suitable function $R(x)$ in part (i), substitution of $R(x) = a + bx + cx^2$ and

$Q(x) = 1 + 2x + 3x^2$ in the given expression yields a quadratic equation, and equating the coefficients of the powers of x gives $5 = -3b + 2c$, $-2 = -3a + c$, $-3 = -2a + b$.

These three equations are linearly dependent and so their solution is not unique.

Choosing, for example $a = 0$, $b = -3$, $c = -2$ and then $a = 1$, $b = -1$, $c = 1$ gives solutions

which are related by $\frac{1-x+x^2}{1+2x+3x^2} = \frac{1+2x+3x^2-3x-2x^2}{1+2x+3x^2} = 1 + \frac{-3x-2x^2}{1+2x+3x^2}$ i.e. the same bar the

arbitrary constant.

(ii) Rearranging the equation to be solved as $\frac{dy}{dx} + \frac{(\sin x - 2 \cos x)}{(1 + \cos x + 2 \sin x)} y = \frac{(5 - 3 \cos x + 4 \sin x)}{(1 + \cos x + 2 \sin x)}$, the

integrating factor is $e^{\int \frac{(\sin x - 2 \cos x)}{(1 + \cos x + 2 \sin x)} dx} = e^{-\ln(1 + \cos x + 2 \sin x)} = \frac{1}{1 + \cos x + 2 \sin x}$

As a result, the RHS we require to integrate is $\frac{(5 - 3 \cos x + 4 \sin x)}{(1 + \cos x + 2 \sin x)^2}$

Repeating similar working to part (i), except with $Q(x) = 1 + \cos x + 2 \sin x$ and

$R(x) = a + b \sin x + c \cos x$, gives three linearly dependent equations,

$$5 = b - 2c, -3 = b - 2a, 4 = a - c$$

Choosing e.g. $a = 4, b = 5, c = 0$, the solution is $y = 4 + 5 \sin x + k(1 + \cos x + 2 \sin x)$

Section B: Mechanics

9. Resolving radially inwards for the mass P , $mg \sin \theta - R = \frac{mv^2}{a}$,

where R is the normal reaction of the block on P , and v is the (common) speed of the masses when OP makes an angle θ with the table.

Conserving energy, $\frac{1}{2}mv^2 + \frac{1}{2}Mv^2 + mga \sin \theta - Mga\theta = 0$, and making v^2 the subject of this formula to substitute in the first equation re-arranged for R ,

$$R = mg \sin \theta - \frac{2mg(M\theta - m \sin \theta)}{m+M} = \frac{mg((3m+M) \sin \theta - 2M\theta)}{m+M}$$
 is found.

Remaining in contact requires this expression to be non-negative for all θ , $0 \leq \theta \leq \frac{\pi}{2}$.

Considering the graphs of $y = a \sin \theta$ and $y = b\theta$ for $0 \leq \theta \leq \frac{\pi}{2}$,

$a \sin \theta - b\theta \geq 0, \forall \theta, 0 \leq \theta \leq \frac{\pi}{2}$ if and only if $a \sin \theta - b\theta \geq 0$ for $\theta = \frac{\pi}{2}$

so $R \geq 0$ for all $\theta, 0 \leq \theta \leq \frac{\pi}{2}$ if and only if $(3m + M) \sin \frac{\pi}{2} - 2M \frac{\pi}{2} \geq 0$ which gives the required result.

10. Resolving perpendicularly to OB , $ma\ddot{\phi} = -T \cos\left(\frac{\pi}{2} - \theta - \phi\right)$, where the tension in the elastic string is $T = \lambda \frac{PB-c}{c}$. The sine rule $\frac{a}{\sin \theta} = \frac{PB}{\sin \phi}$

Putting these three results together gives the required expression.

Also from the sine rule, $\frac{b}{\sin(\theta+\phi)} = \frac{a}{\sin \theta}$, so for ϕ and θ small, $\frac{b}{\theta+\phi} \approx \frac{a}{\theta}$ yielding the desired result.

From this result, θ may be made the subject of the formula, so that the result

$$ma\ddot{\phi} = -\lambda \left(\frac{a \sin \phi}{c \sin \theta} - 1 \right) \sin(\theta + \phi),$$
 which for small angles becomes

$$ma\ddot{\phi} \approx -\lambda \left(\frac{a\phi}{c\theta} - 1 \right) (\theta + \phi)$$
 can be written $\ddot{\phi} \approx -\frac{\lambda}{ma} \left(\frac{b-a-c}{c} \right) \left(\frac{b}{b-a} \right) \phi$

and hence the period is $\tau \approx 2\pi \sqrt{\frac{mac(b-a)}{\lambda b(b-a-c)}}$.

11. If the acceleration of the block is a' , and the acceleration of the bullet is a'' , then $R - \mu(M + m)g = Ma'$ and $-R = ma''$,
 so the relative acceleration $a = a' - a'' = \frac{R}{m} + \frac{R - \mu(M + m)g}{M}$

The initial velocity of the bullet relative to the block is $-u$ and the final velocity of the bullet relative to the block is 0. If the time between the bullet entering the block and stopping moving through the block is T , then using " $v = u + at$ ", $0 = -u + \left(\frac{R}{m} + \frac{R - \mu(M + m)g}{M}\right)T$
 For the block, the initial velocity is 0, the final velocity is v , and again using $v = u + at$,

$$v = a'T = \frac{R - \mu(M + m)g}{M} \frac{u}{\left(\frac{R}{m} + \frac{R - \mu(M + m)g}{M}\right)} \text{ and so}$$

$$av = \left(\frac{R}{m} + \frac{R - \mu(M + m)g}{M}\right) \frac{R - \mu(M + m)g}{M} \frac{u}{\left(\frac{R}{m} + \frac{R - \mu(M + m)g}{M}\right)} = \frac{Ru - \mu(M + m)gu}{M} \text{ as required.}$$

If the distance moved by the block whilst the bullet is moving through the block is s , using " $v^2 = u^2 + 2as$ ", $v^2 = 2a's$ and so $s = \frac{v^2}{2a'} = \frac{Mv^2}{2(R - \mu(M + m)g)} = \frac{Mv^2}{2\frac{Mav}{u}} = \frac{uv}{2a}$

Once the bullet stops moving through the block, the next initial velocity of block/bullet is v , the final velocity is 0, the acceleration is $-\mu g$, so the distance moved s' using

$$"v^2 = u^2 + 2as" \text{ is given by } 0 = v^2 - 2\mu g s' \text{ i.e. } s' = \frac{v^2}{2\mu g}$$

$$\text{Thus the total distance moved is } \frac{uv}{2a} + \frac{v^2}{2\mu g} = \frac{v}{2\mu ga} [\mu gu + av]$$

$$= \frac{v}{2\mu ga} \left[\mu gu + \frac{Ru - \mu(M + m)gu}{M} \right]$$

$$= \frac{uv}{2\mu g} \left[\frac{R - \mu mg}{Ma} \right]$$

$$= \frac{uv}{2\mu g} \left[\frac{R - \mu mg}{M} \right] \frac{1}{\frac{R}{m} + \frac{R - \mu(M + m)g}{M}}$$

$$= \frac{uv}{2\mu g} \left[\frac{R - \mu mg}{M} \right] \frac{Mm}{(M + m)(R - \mu mg)} = \frac{muv}{2(M + m)\mu g}$$

If $R < (M + m)\mu g$, then the block does not move, and the bullet penetrates to a depth $\frac{mu^2}{2R}$.

Section C: Probability and Statistics

12. $S - rS = 1 + dr + dr^2 + \dots + dr^n + \dots$ which is 1 plus an infinite GP. Summing that GP and making S the subject produces the displayed result.

$$E(A) = 1a + 2(1 - a)a + 3(1 - a)^2a + \dots + n(1 - a)^{n-1}a + \dots \text{ so making use of the first result with } d = 1, r = (1 - a), E(A) = a \left\{ \frac{1}{1 - (1 - a)} + \frac{(1 - a)}{(1 - (1 - a))^2} \right\} = a \left\{ \frac{1}{a} + \frac{1 - a}{a^2} \right\} = \frac{1}{a}$$

$\alpha = a + (1 - a)(1 - b)\alpha = a + a'b'\alpha$ or alternatively, $\alpha = a + a'b'a + a'^2b'^2a + \dots$ which both lead to the required result.

$$\beta = 1 - \alpha = \frac{a'b}{1 - a'b'} \text{ or alternatively, } \beta = a'b + a'^2b'b + a'^3b'^2b + \dots = \frac{a'b}{1 - a'b'}$$

The expected number of shots, S, is given by

$$E(S) = 1a + 2a'b + 3a'b'a + 4a'^2b'b + 5a'^2b'^2a + \dots \\ = a\{1 + 3a'b' + 5a'^2b'^2 + \dots\} + 2a'b\{1 + 2a'b' + \dots\}$$

which using the initial result of the question $= a\left[\frac{1}{1 - a'b'} + \frac{2a'b'}{(1 - a'b')^2}\right] + 2a'b\left[\frac{1}{1 - a'b'} + \frac{a'b'}{(1 - a'b')^2}\right]$ and can be shown to simplify to the required expression.

$$13. \text{Corr}(Z_1, Z_2) = 0$$

$$E(Y_2) = E\left(\rho_{12}Z_1 + (1 - \rho_{12}^2)^{\frac{1}{2}}Z_2\right) = \rho_{12}E(Z_1) + (1 - \rho_{12}^2)^{\frac{1}{2}}E(Z_2) = 0$$

$$\text{Var}(Y_2) = \text{Var}\left(\rho_{12}Z_1 + (1 - \rho_{12}^2)^{\frac{1}{2}}Z_2\right) = \rho_{12}^2\text{Var}(Z_1) + (1 - \rho_{12}^2)\text{Var}(Z_2) \\ = \rho_{12}^2 + (1 - \rho_{12}^2) = 1$$

As $E(Y_1) = E(Y_2) = 0$ and $\text{Var}(Y_1) = \text{Var}(Y_2) = 1$,

$$\text{Corr}(Y_1, Y_2) = \frac{\text{Cov}(Y_1, Y_2)}{\sqrt{\text{Var}(Y_1)\text{Var}(Y_2)}} = \text{Cov}(Y_1, Y_2) = E(Y_1Y_2) - E(Y_1)E(Y_2) \\ = E\left(\rho_{12}Z_1^2 + (1 - \rho_{12}^2)^{\frac{1}{2}}Z_1Z_2\right) = \rho_{12}\text{Var}(Z_1) + (1 - \rho_{12}^2)^{\frac{1}{2}}E(Z_1)E(Z_2) = \rho_{12}$$

$E(Y_3) = E(aZ_1 + bZ_2 + cZ_3) = aE(Z_1) + bE(Z_2) + cE(Z_3) = 0$ is given.

$\text{Var}(Y_3) = 1$ implies $a^2 + b^2 + c^2 = 1$

$\text{Corr}(Y_1, Y_3) = \rho_{13}$ implies $a = \rho_{13}$ as seen before.

$$\text{Corr}(Y_2, Y_3) = \rho_{23} \text{ implies } \rho_{12}a + (1 - \rho_{12}^2)^{\frac{1}{2}}b = \rho_{23}$$

$$\text{and hence } a = \rho_{13}, b = \frac{\rho_{23} - \rho_{12}\rho_{13}}{(1 - \rho_{12}^2)^{\frac{1}{2}}}, c = \sqrt{1 - \rho_{13}^2 - \frac{(\rho_{23} - \rho_{12}\rho_{13})^2}{(1 - \rho_{12}^2)}}$$

$X_i = \mu_i + \sigma_i Y_i$ for $i = 1, 2, 3$ as $E(X_i) = E(\mu_i + \sigma_i Y_i) = E(\mu_i) + E(\sigma_i Y_i) = \mu_i + \sigma_i E(Y_i) = \mu_i$,

$\text{Var}(X_i) = \text{Var}(\mu_i + \sigma_i Y_i) = \text{Var}(\sigma_i Y_i) = \sigma_i^2 \text{Var}(Y_i) = \sigma_i^2$, and

$\text{Corr}(X_i, X_j) = \text{Corr}(Y_i, Y_j) = \rho_{ij}$ as a linear transformation does not affect correlation.